

STABILITY AND GLOBAL ATTRACTIVITY FOR A CLASS OF NONLINEAR DELAY DIFFERENCE EQUATIONS

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A class of nonlinear delay difference equations are considered and some sufficient conditions for global attractivity of solutions of the equation are obtained. It is shown that the stability properties, both local and global, of the equilibrium of the delay equation can be derived from those of an associated nondelay equation.

1. Introduction

Consider the following nonlinear delay difference equations

$$x(n+1) = cx(n) + f(x(n) - x(n-k)), \quad (1.1)$$

where $c \in [0, 1)$ is a given constant, k is a positive integer, $f : R \rightarrow R$ is continuous and $f(0) = 0$, $f(u) \neq 0$ for $u \neq 0$. Such a equation arises from some of the earliest mathematical models of the macroeconomic "trade cycle," and have attracted a great deal of attention (see, e.g., [1, 4, 5, 6, 7, 8, 9, 10] and references cited therein). When $k = 1$, Sedaghat [9] obtained some sufficient conditions for the permanence and boundedness by exploring the relationship between the first order equations and the higher order equations.

Our main goal in this paper is to obtain some sufficient conditions which guarantee that the equilibrium of (1.1) is a global attractor. We still investigate the stability of (1.1) and show that the stability properties, both local and global, of the equilibrium of the delay equation (1.1) can be derived from those of the associated nondelay equation

$$x(n+1) = f(x(n)), \quad (1.2)$$

where the f is the same function as in (1.1). This result is of considerable benefit to the study of delay-difference equations of this type since the stability properties of nondelay difference equations are better understood [2, 3].

A point \bar{x} is called an equilibrium of (1.1) if $x(n) = \bar{x}$ ($n \geq 0$) is a solution of (1.1). It is obvious that (1.1) has the only equilibrium $\bar{x} = 0$ under the hypothesis.

We say that the equilibrium $\bar{x} = 0$ of (1.1) is a global attractor if and only if, for arbitrary initial conditions, the corresponding solution $x(n)$ of (1.1) satisfies $\lim_{n \rightarrow \infty} x(n) = 0$. The region of attraction of the equilibrium $\bar{x} = 0$ is defined as the set of all initial points $\{x(-k), x(-k+1), \dots, x(0)\}$ such that $\lim_{n \rightarrow \infty} x(n) = 0$.

Without loss generality, throughout this paper the norm will be defined as

$$\|x\| = \max_{1 \leq i \leq m} |x_i|, \quad x \in R^m. \tag{1.3}$$

The rest of the paper is organized as follows. In Section 2, we derive a sufficient condition for global attractivity of the equilibrium of (1.1). In Section 3, we discuss the stability properties of (1.1).

2. Global Attractivity of (1.1)

The objective of this section is to derive sufficient conditions which guarantee that the equilibrium of (1.1) is a global attractor. Let

$$u(n) = x(n) - x(n - k). \tag{2.1}$$

Then (1.1) is reduced to:

$$u(n + 1) = cu(n) + f(u(n)) - f(u(n - k)). \tag{2.2}$$

Noting that $c \in [0, 1)$, (2.2) has the unique equilibrium $\bar{u} = 0$. We first show the following proposition.

PROPOSITION 2.1. *Assume that there exist a constant $\alpha \in (0, 1)$ such that $\alpha + c < 1$ and*

$$|f(u)| \leq \alpha|u| \tag{2.3}$$

for all u . Then every solution $u(n)$ of (2.2) satisfies

$$\lim_{n \rightarrow \infty} u(n) = 0. \tag{2.4}$$

Proof. By (2.2) and the assumption of f , we have

$$\begin{aligned} |u(n + 1)| &= |cu(n) + f(u(n)) - f(u(n - k))| \\ &\leq c|u(n)| + \alpha|u(n)| + \alpha|u(n - k)| \\ &= (\alpha + c)|u(n)| + \alpha|u(n - k)|, \end{aligned} \tag{2.5}$$

for $n = 0, 1, \dots$. Using induction and noting that $0 < \alpha < 1$ and $\alpha + c < 1$, we have

$$\lim_{n \rightarrow \infty} |u(n)| = 0, \tag{2.6}$$

which implies that $\lim_{n \rightarrow \infty} u(n) = 0$. The proof is complete. □

The following theorem gives a sufficient condition for the equilibrium $\bar{x} = 0$ of (1.1) to be a global attractor.

THEOREM 2.2. *If the condition (2.3) holds, then every solution of (1.1) converges to $\bar{x} = 0$.*

Proof. Let

$$u(n) = x(n) - x(n - k). \tag{2.7}$$

Then (1.1) can be written as

$$x(n + 1) = cx(n) + f(u(n)), \quad \text{for } n = 0, 1, \dots \tag{2.8}$$

So we have

$$\begin{aligned} x(1) &= cx(0) + f(u(0)), \\ x(2) &= cx(1) + f(u(1)) = c^2x(0) + cf(u(0)) + f(u(1)). \end{aligned} \tag{2.9}$$

By induction, we get

$$x(n) = c^n x(0) + \sum_{i=0}^{n-1} c^{n-1-i} f(u(i)). \tag{2.10}$$

Noting that $c \in [0, 1)$, we have

$$\lim_{n \rightarrow \infty} c^n x(0) = 0. \tag{2.11}$$

Let

$$\tilde{u}(n) = \sum_{i=0}^{n-1} c^{n-1-i} f(u(i)). \tag{2.12}$$

We distinguish two cases to prove

$$\lim_{n \rightarrow \infty} \tilde{u}(n) = 0. \tag{2.13}$$

Case 1 ($\sum_{i=0}^{\infty} f(u(i))/c^i < \infty$). In this case, it is obvious that $\lim_{n \rightarrow \infty} \tilde{u}(n) = 0$ since $\lim_{n \rightarrow \infty} c^{n-1} = 0$.

Case 2 ($\sum_{i=0}^{\infty} f(u(i))/c^i = \infty$). By Stolz Theorem, we have

$$\begin{aligned} \lim_{n \rightarrow \infty} \tilde{u}(n) &= \lim_{n \rightarrow \infty} \frac{\sum_{i=0}^{n-1} (f(u(i))/c^i)}{1/c^{n-1}} \\ &= \lim_{n \rightarrow \infty} \frac{\sum_{i=0}^n (f(u(i))/c^i) - \sum_{i=0}^{n-1} (f(u(i))/c^i)}{(1/c^n) - (1/c^{n-1})} \\ &= \lim_{n \rightarrow \infty} \frac{f(u(n))/c^n}{(1 - c)/c^n} \\ &= \frac{1}{1 - c} \lim_{n \rightarrow \infty} f(u(n)). \end{aligned} \tag{2.14}$$

Using the continuity of the function f and Proposition 2.1, we have

$$\lim_{n \rightarrow \infty} f(u(n)) = 0. \tag{2.15}$$

Thus

$$\lim_{n \rightarrow \infty} \tilde{u}(n) = 0. \tag{2.16}$$

Finally (2.11) and (2.13) imply that $\lim_{n \rightarrow \infty} x(n) = 0$. The proof is completed. \square

3. Stability of (1.1)

Let $x(n)$ be a solution of (1.1). We defined the vector $y(n) \in R^{k+1}$ as $y(n) = (y_1(n), \dots, y_{k+1}(n))^T$, where

$$y_j(n) = x(n + j - k - 1), \quad j = 1, 2, \dots, k + 1. \tag{3.1}$$

Then the delay equation (1.1) is equivalent to the following $(k + 1)$ -dimensional system

$$y(n + 1) = g(y(n)), \quad y(n) \in R^{k+1}, \tag{3.2}$$

where $g(y) = (g_1(y), g_2(y), \dots, g_{k+1}(y))^T$ with

$$g_j(y(n)) = y_{j+1}(n), \quad j = 1, 2, \dots, k, \tag{3.3}$$

$$g_{k+1}(y(n)) = cy_{k+1}(n) + f(y_{k+1}(n) - y_1(n)). \tag{3.4}$$

It is obvious that $\bar{y} = 0$ is the only equilibrium of the system (3.2).

In this section, we present the main results which relate the stability properties of the delay equation (1.1) to those of the associated nondelay equation

$$x(n + 1) = f(x(n)), \quad n \geq -k. \tag{3.5}$$

First we establish a lemma which will be used in proving the main theorem.

LEMMA 3.1. *Let $y(n)$ be a solution of the system (3.2). Then for $j = 1, 2, \dots, k + 1$, the following statements are true:*

(a)

$$y_j(n) = y_{j+n}(0), \quad 0 \leq n \leq k + 1 - j; \tag{3.6}$$

(b)

$$\begin{aligned} |y_j(n)| &\leq c^{n+j-k-1} |y_{k+1}(0)| \\ &+ \sum_{i=0}^{n+j-k-2} c^{n+j-k-2-i} |f(y_{k+1}(i) - y_1(i))|, \quad n \geq k + 2 - j. \end{aligned} \tag{3.7}$$

Proof. From (3.3), we have

$$\begin{aligned} y_{k+1}(n) &= cy_{k+1}(n-1) + f(y_{k+1}(n-1) - y_1(n-1)) \\ &= c^n y_{k+1}(0) + \sum_{i=0}^{n-1} c^{n-1-i} f(y_{k+1}(i) - y_1(i)). \end{aligned} \tag{3.8}$$

Now let $1 \leq j \leq k+1$. Equation (3.3) also implies

$$y_j(n) = y_{j+1}(n-1) = y_{j+n}(0), \quad \text{for } 0 \leq n \leq k+1-j, \tag{3.9}$$

which leads to (a), and

$$y_j(n) = y_{k+1}(n+j-k-1), \quad \text{for } n \geq k+2-j. \tag{3.10}$$

Combined with (3.8), this yields, for $n \geq k+2-j$, that

$$y_j(n) = c^{n+j-k-1} y_{k+1}(0) + \sum_{i=0}^{n+j-k-2} c^{n+j-k-2-i} f(y_{k+1}(i) - y_1(i)). \tag{3.11}$$

This leads to the inequality (3.7), and thus, (b) holds. The proof is completed. □

THEOREM 3.2. *Assume f satisfies*

$$|f(x+y)| \leq |f(x)| + |f(y)|, \tag{3.12}$$

for all $x, y \in R$. If the equilibrium of (3.5) is stable, then the equilibrium of (1.1) is also stable.

Proof. It is sufficient to prove the stability of the equilibrium of (3.2) because of the equivalence of (1.1) and (3.2).

Let $\epsilon > 0$ be arbitrary. Since the equilibrium of (3.5) is stable, there exists $\delta_1 > 0$ such that $|x(-k)| < \delta_1$ implies $|x(n)| < (1-c)\epsilon/2$ for all $n \geq -k$. Now choose $\delta = \min(\delta_1, (1-c)\epsilon/2)$, Then $\|y(0)\| < \delta$ implies $|x(-k)| < \delta \leq \delta_1$ from the definition of y given by (3.1). Hence,

$$|x(n)| < \frac{(1-c)\epsilon}{2}, \tag{3.13}$$

for all $n \geq -k$, which implies

$$|f(x(n))| < \frac{(1-c)\epsilon}{2}, \tag{3.14}$$

for all $n \geq -k$. Therefore, for all $n \geq 0$, by (3.1)

$$|f(y_{k+1}(n))| < \frac{(1-c)\epsilon}{2}, \quad |f(y_1(n))| < \frac{(1-c)\epsilon}{2}. \tag{3.15}$$

Noting that f satisfies

$$|f(x+y)| \leq |f(x)| + |f(y)|, \tag{3.16}$$

we get

$$|f(y_{k+1}(n) - y_1(n))| < (1 - c)\epsilon. \tag{3.17}$$

Now $\|y(0)\| < \delta$ implies that $|y_j(0)| < \delta \leq (1 - c)\epsilon/2 < \epsilon$ for $1 \leq j \leq k + 1$. Hence, from Lemma 3.1(a),

$$|y_j(n)| = |y_{j+n}(0)| < \epsilon, \quad \text{for } 0 \leq n \leq k + 1 - j, \tag{3.18}$$

and from Lemma 3.1(b) and (3.17),

$$\begin{aligned} |y_j(n)| &< \epsilon c^{n+j-k-1} + (1 - c)\epsilon \frac{c^{n+j-k-2} - 1/c}{1 - 1/c} \\ &= \epsilon c^{n+j-k-1} + \epsilon(1 - c) \frac{1 - c^{n+j-k-1}}{1 - c} \\ &= \epsilon, \quad \text{for } n \geq k + 2 - j. \end{aligned} \tag{3.19}$$

Therefore, for arbitrary $\epsilon > 0$, there exists $\delta > 0$, such that $\|y(0)\| < \delta$ implies $\|y(n)\| < \epsilon$ for $n \geq 0$, so the equilibrium of (3.2) is stable. This completes the proof. \square

THEOREM 3.3. *Assume that (3.12) holds. If there exists a constant $m > 0$ such that $G(m) = \{x \in R \mid |x| < m\}$ is a subset of attractive region of the equilibrium of (3.2), then $G(m)$ is also contained in the attractive region of the equilibrium of (1.1).*

Proof. Let $\epsilon > 0$ be arbitrary. Since $G(m)$ is a subset of attractive region of (3.2), there exists $T_1(m, \epsilon)$ such that $|x(-k)| < m$ implies $|x(n)| < \epsilon$ for $n \geq T_1$.

Assume that $y(0) \in R^{k+1}$ and $\|y(0)\| < m$, then we have $|x(-k)| < m$. So there exists $T_2(m, (1 - c)\epsilon/4) \geq T_1$ such that $|x(n)| < (1 - c)\epsilon/4$ for all $n \geq T_2$, which implies, by (3.1) and (3.12), that

$$|f(y_{k+1}(n) - y_1(n))| < \frac{(1 - c)\epsilon}{2} \tag{3.20}$$

for all $n \geq T_2 + k$. Let $1 \leq j \leq k + 1$. By Lemma 3.1, we have

$$|y_j(n)| < mc^{n+j-k-1} + \frac{\epsilon}{2} + \sum_{i=0}^{T_2+k-1} c^{n+j-k-2-i} |f(y_{k+1}(i) - y_1(i))| \tag{3.21}$$

provided $n \geq k + 2 - j$ which is true for $n \geq k + 1$. Now

$$\begin{aligned} |f(y_{k+1}(i) - y_1(i))| &= |f(x(i) - x(i - k))| \\ &\leq |f(x(i))| + |f(x(i - k))| \\ &= |f^{i+k+1}(x(-k))| + |f^{i+1}(x(-k))|, \end{aligned} \tag{3.22}$$

where $f^j = \underbrace{f \circ f \circ \dots \circ f}_j$ means the function f composed with itself j times. The continuity of f implies that f^j is also continuous, and so there exists $L > 0$ such that $|f^{i+k+1}(x(-k))| < L$ and $|f^{i+1}(x(-k))| < L$. From (3.21), we obtain for $n \geq T_2 + 2k$

$$\begin{aligned}
 |y_j(n)| &< mc^{n+j-k-1} + \frac{\epsilon}{2} + 2L \sum_{i=0}^{T_2+k-1} c^{n+j-k-2-i} \\
 &< \left(m + \frac{2L}{1-c}\right)c^{n+j-2k-1-T_2} + \frac{\epsilon}{2}.
 \end{aligned}
 \tag{3.23}$$

Now choose T_3 such that

$$\left(m + \frac{2L}{1-c}\right)c^{n+j-2k-1-T_2} \leq \frac{\epsilon}{2}
 \tag{3.24}$$

holds for $n \geq T_3$, that is

$$T_3 \geq T_2 + 2k + \frac{\ln(\epsilon/2(m + (2L/(1-c))))}{\ln c}.
 \tag{3.25}$$

Then $\|y(0)\| < m$ implies $\|y(n)\| < \epsilon$ for $n \geq T_3$. So $G(m)$ is also a subset of attractive region of the equilibrium of (1.1). This completes the proof. \square

Theorems 3.2 and 3.3 can be combined to give the following corollaries.

COROLLARY 3.4. *Assume that the condition (3.12) holds. If the equilibrium of (3.5) is asymptotically stable, then the equilibrium of (1.1) is also asymptotically stable.*

COROLLARY 3.5. *Assume that the condition (3.12) holds. If the equilibrium of (3.5) is globally stable, then the equilibrium of (1.1) is also globally stable.*

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